

ROBOTIC OBSERVATIONS OF INTEGRAL SOURCES IN THE OPTICAL DOMAIN

Petr Kubánek^{1,2,4}, René Hudec¹, John French^{3,4}, Jan Štrobl¹, Martin Nekola¹, and Filip Munz¹

¹*Astronomický ústav Akademie věd České republiky, Ondřejov, Czech Republic*

²*INTEGRAL Science Data Center, Chemin d'Ecogia 16, Versoix, Switzerland*

³*University College Dublin, Dublin, Ireland*

⁴*for the Watcher Collaboration*

ABSTRACT

We present the status of our ground-based instruments (robotic telescopes), which are (among other tasks) used for monitoring of INTEGRAL gamma-ray sources, mostly AGNs and blazars, as well as selected cataclysmic variables, at optical wavelengths. At the same time, these robotic devices serve as fast optical alert systems to follow GRB alerts provided by INTEGRAL.

Key words: robotic telescopes, INTEGRAL.

1. MOTIVATION

Only a fraction of the 209 gamma-ray sources detected by the INTEGRAL satellite are either known sources or have been identified and classified already. From the 56 new (IGR) sources detected by INTEGRAL, only 20% have already been firmly classified, mostly with Cataclysmic Variables (CVs), AGNs, High Mass X-ray Binaries, Low Mass X-ray Binaries, Black Hole Candidates, and Anomalous X-ray Pulsars[1]. One of the methods applied in the past is identification by spectroscopy, which recently provided some new and interesting identifications of INTEGRAL gamma-ray sources such as newly detected symbiotic and cataclysmic variables [5], [6]).

Numerous newly detected and already identified INTEGRAL gamma-ray sources have variable optical counterparts with magnitudes that allow them to be observed by small aperture optical robotic CCD telescopes. As those objects are newly identified, no optical light curves are available, with the exception of automatically generated curves by very small monitoring devices with low accuracy. On the other hand, the analyses of well sampled and accurate optical light curves and their comparison with light curves at higher energies can give valuable additional insights into the related physical processes and evolution of the sources.

The additional prospects of optical monitoring of INTEGRAL sources by robotic telescopes are represented by analysing their light curves for flares and flaring activity,

trying to fit the flare profiles, trying to look for possible periodicities and recurrences, and the study of colours and colour changes with time, with consequent discussions and interpretations. The related science includes classification of the observed objects, with conclusions toward physical processes and models.

The last aspect of monitoring by robotic telescopes for INTEGRAL sources is the imaging of positions of non-classified newly detected gamma-ray sources at different times. This can represent an alternative approach to identification and classification of targets, based on the detection of variable optical counterparts inside the error boxes of the sources.

2. INSTRUMENTS

Instruments which are available to us for observations are listed in table 1. All these instruments are controlled by RTS2[4], and are used for TOO observations of GRB triggers distributed by GCN.

Besides these instruments we can also trigger TOO observations on other, larger telescopes.

The sources are monitored with BART[3]. Southern coverage is partly provided by Watcher[2]. BART and Watcher targets statistics is provided in tables 2, 3 and 4, and some images are shown in this paper.

3. DATA PROCESSING

The PostgreSQL database can be searched for images that contain a given object. We have accessed the image archive using a simple WWW based interface. We now aim to create a Virtual Observatory compliant interface, which will provide access to images and light curves.

| Name | From | Location |
|----------------|------|--|
| BART | 2000 | Ondřejov, Czech Republic |
| BOOTES-1A | 2003 | El Arenosillo (CEDEA-INTA), Spain |
| BOOTES-1B | 2003 | El Arenosillo (CEDEA-INTA), Spain |
| BOOTES-2 | 2003 | La Mayora (EELM-CSIC), Spain |
| BOOTES-IR | 2005 | OSN, IAA-CSIC, Spain |
| FRAM | 2005 | Pierre Auger south observatory, Argentina |
| Watcher | 2006 | Boyden Observatory, Republic of South Africa |

Table 1. Instruments.

4. DATA ONLINE ACCESS

Data is accessible through RTS2-Web interface. An example of it can be seen on BART web, <http://zeus.asu.cas.cz/rts2-web>.

5. FUTURE DEVELOPMENT

We have developed a platform which enables us to operate robotic telescopes, each based on different hardware, performing different tasks, but running the same software.

As our instruments now run in unattended mode for months at a time, we are now trying to manage the data volumes they produce. We are currently developing an autonomous analytic pipeline which will send us reports about deviations of selected sources from expected behaviour. Unfortunately, this task is more difficult than we initially expected, and it will take some time before this pipeline reaches maturity and its results will be of sufficient quality for publication.

6. CONCLUSIONS

The robotic observations of INTEGRAL sources represent a valuable additional data source for investigation of their behaviour and evolution when they are already identified with optical sources with magnitudes within the range of the used telescopes, or, alternatively, for identification and classification of non-identified sources by comparing CCD images taken at various different epochs. This represent huge amounts of acquired data, hence the development of relevant and reliable programmes is necessary. This development is underway.

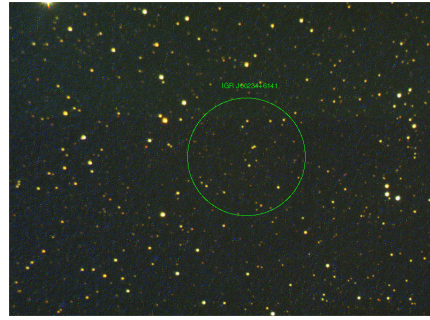


Figure 1. IGR J00234+6141 error box.

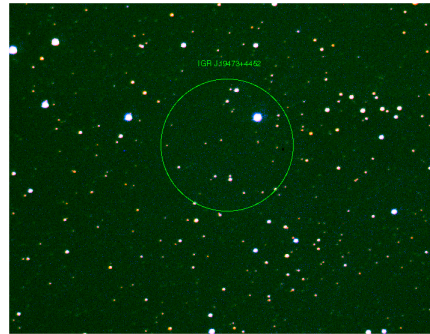


Figure 2. IGR J19473+4452 error box.

7. ACKNOWLEDGEMENTS

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| Name | RA (J2000) | DEC (J2000) | Images | Processed |
|-----------------|-------------|-------------|--------|-----------|
| | HH MM SS.ss | DEG MM SS.s | | |
| OES 2132+50.9 | 21 33 43.68 | +51 07 24.8 | 296 | 199 |
| IGR J00234+6141 | 00 23 24.00 | +61 41 32.0 | 75 | 35 |
| IGR J00291+5934 | 00 29 03.06 | +59 34 19.0 | 34 | 9 |
| BD+60 73 | 00 37 09.64 | +61 21 36.5 | 42 | 16 |
| IGR J01363+6610 | 01 36 18.00 | +66 10 36.0 | 123 | 28 |
| IGR J06074+2205 | 06 07 24.00 | +22 05 00.0 | 133 | 36 |
| IGR J12391-1612 | 12 39 06.24 | -16 10 47.3 | 47 | 1 |
| NGC 4992 | 13 09 05.52 | +11 38 02.8 | 483 | 138 |
| 1H 1726-058 | 17 30 21.60 | -05 59 34.0 | 22 | 20 |
| IGR J01363+661 | 01 36 18.00 | +66 10 36.1 | 121 | 29 |
| IGR J06074+2205 | 06 07 24.00 | +22 05 00.0 | 154 | 33 |
| IGR J12391-1612 | 12 39 06.24 | -16 10 47.3 | 53 | 1 |
| NGC 4992 | 13 09 05.52 | +11 38 02.8 | 338 | 93 |
| 1H 1726-058 | 17 30 21.60 | -05 59 34.0 | 11 | 10 |
| IGR J18539+0727 | 18 53 54.00 | +07 27 29.0 | 62 | 48 |
| IGR J19140+0951 | 19 14 04.32 | +09 52 58.3 | 53 | 37 |
| IGR J19308+0530 | 19 30 46.08 | +05 30 07.0 | 11 | 11 |
| IGR J19473+4452 | 19 47 19.44 | +44 49 42.2 | 1618 | 1328 |
| IGR J21247+5058 | 21 24 31.92 | +50 58 08.0 | 296 | 177 |
| IGR J21335+5105 | 21 33 30.00 | +51 05 30.8 | 279 | 209 |

Table 2. Targets in BART database with observations.

| Name | RA (J2000) | DEC (J2000) | Images | Processed |
|------------|-------------|-------------|--------|-----------|
| | HH MM SS.ss | DEG MM SS.s | | |
| V* RT Cru | 12 34 53.74 | -64 33 56.0 | 2355 | 2261 |
| CD-57 3057 | 10 11 02.95 | -57 48 13.9 | 3561 | 3485 |

Table 3. Targets in Watcher database with observations.

| Name | RA (J2000) | DEC (J2000) |
|-----------------|-------------|-------------|
| | HH MM SS.ss | DEG MM SS.s |
| IGR J07506-1547 | 07 50 35.04 | -15 47 17.2 |
| IGR J07506-1547 | 07 50 35.04 | -15 47 17.2 |
| IGR J17331-2406 | 17 33 06.00 | -24 07 00.1 |
| IGR J17418-1212 | 17 41 50.88 | -12 11 46.0 |
| IGR J17513-2011 | 17 51 17.04 | -20 11 17.2 |
| IGR J17597-2201 | 17 59 46.08 | -22 01 53.0 |
| IGR J18027-1455 | 18 02 46.08 | -14 56 34.1 |
| IGR J18027-2016 | 18 02 46.08 | -20 17 38.0 |
| IGR J18048-1455 | 18 04 50.88 | -14 54 50.0 |
| IGR J18135-1751 | 18 13 26.88 | -17 50 56.0 |
| IGR J18214-1318 | 18 21 22.08 | -13 18 29.2 |
| IGR J18256-1035 | 18 25 36.96 | -10 35 12.8 |
| IGR J18259-0706 | 18 25 55.92 | -07 06 22.0 |
| IGR J18325-0756 | 18 32 28.08 | -07 56 24.0 |
| IGR J18406-0539 | 18 40 36.00 | -05 39 00.0 |
| IGR J18410-0535 | 18 41 00.48 | -05 35 46.8 |
| IGR J18450-0435 | 18 44 58.08 | -04 36 07.0 |
| IGR J18483-0311 | 18 48 14.88 | -03 10 08.0 |
| IGR J18490-0000 | 18 49 04.08 | -00 01 30.0 |
| IGR J19284+0107 | 19 28 24.00 | +01 07 08.0 |

Table 4. Targets in BART database, which were not yet observed due to observational constraints.